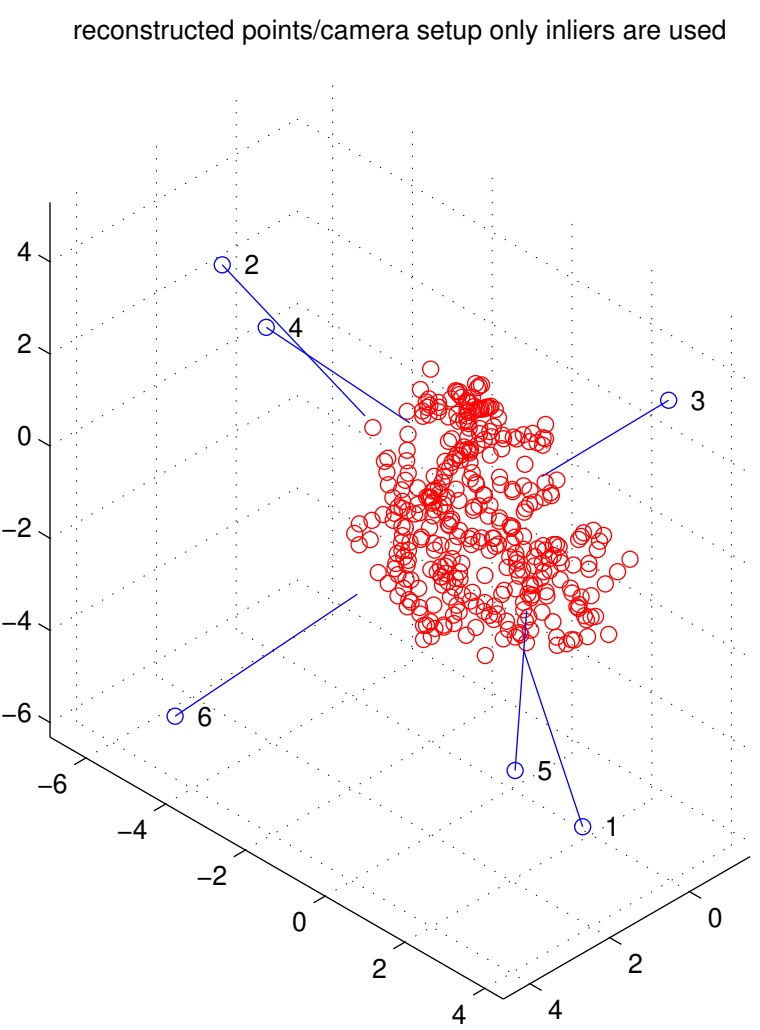
reconstructed points/camera setup only inliers are used
2
4
3
6
5
1
4
2
0
−2
−4
−6
−6
−4
−2
0
2
4
4
2
0