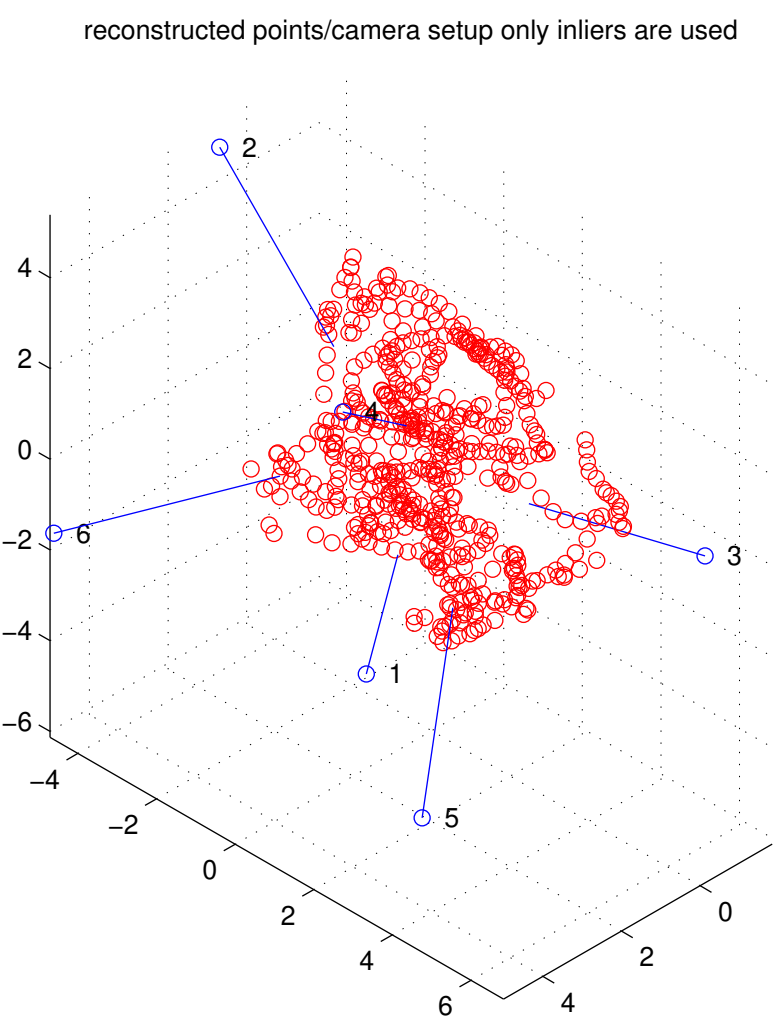
reconstructed points/camera setup only inliers are used
2
4
6
3
1
5
4
2
0
−2
−4
−6
−4
−2
0
2
4
6
0
2
4