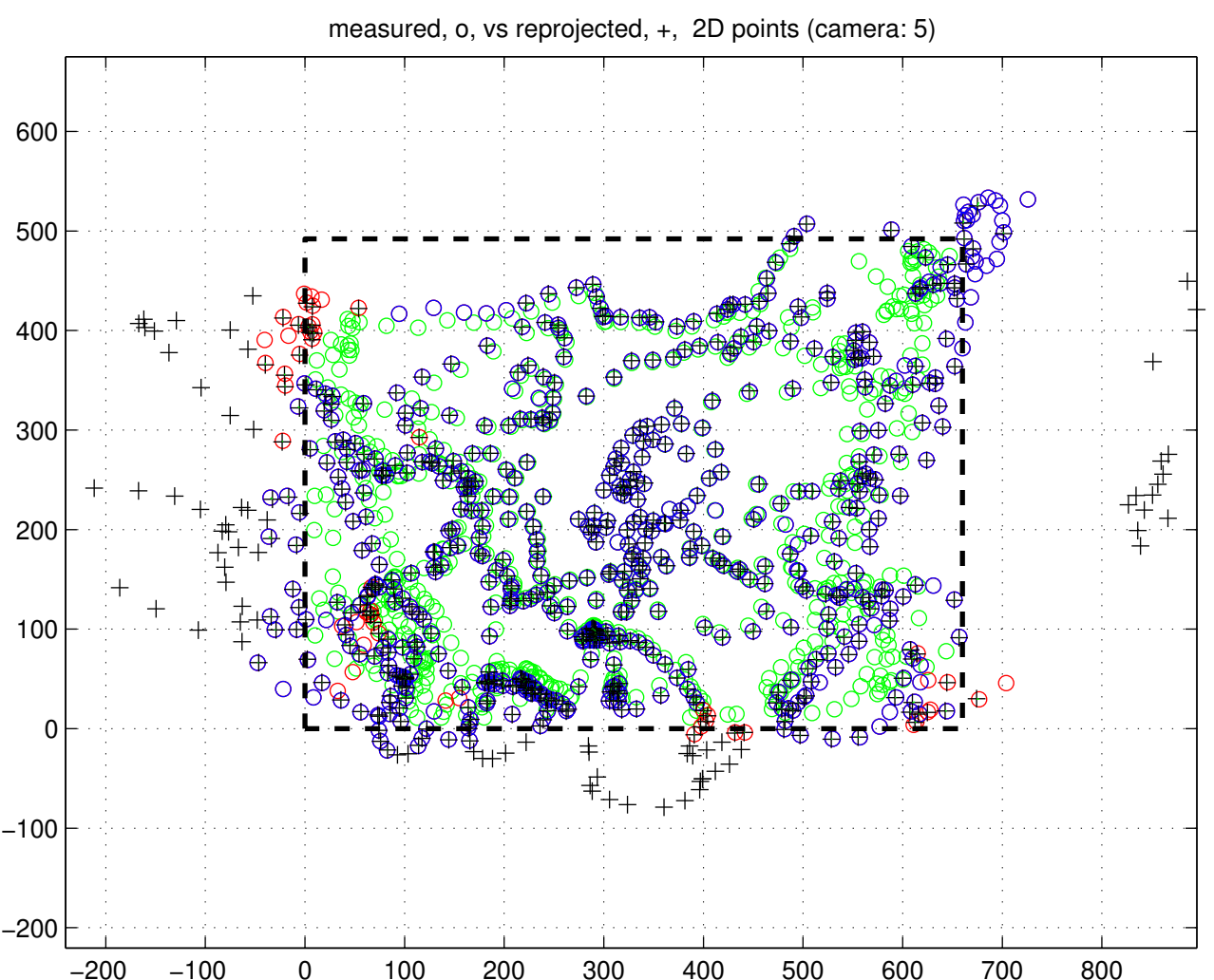
measured, o, vs reprojected, +, 2D points (camera: 5)
600
500
400
300
200
100
0
−100
−200
−200
−100
0
100
200
300
400
500
600
700
800