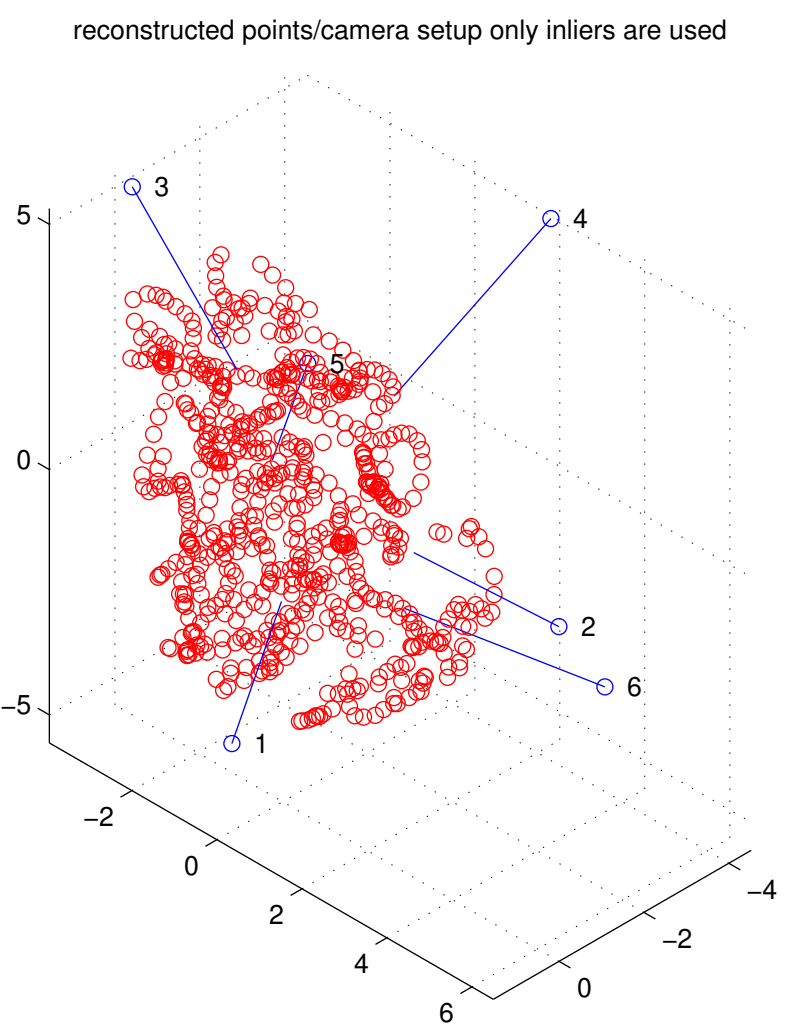
reconstructed points/camera setup only inliers are used
3
4
5
2
6
1
5
0
−5
−2
0
2
4
6
−4
−2
0