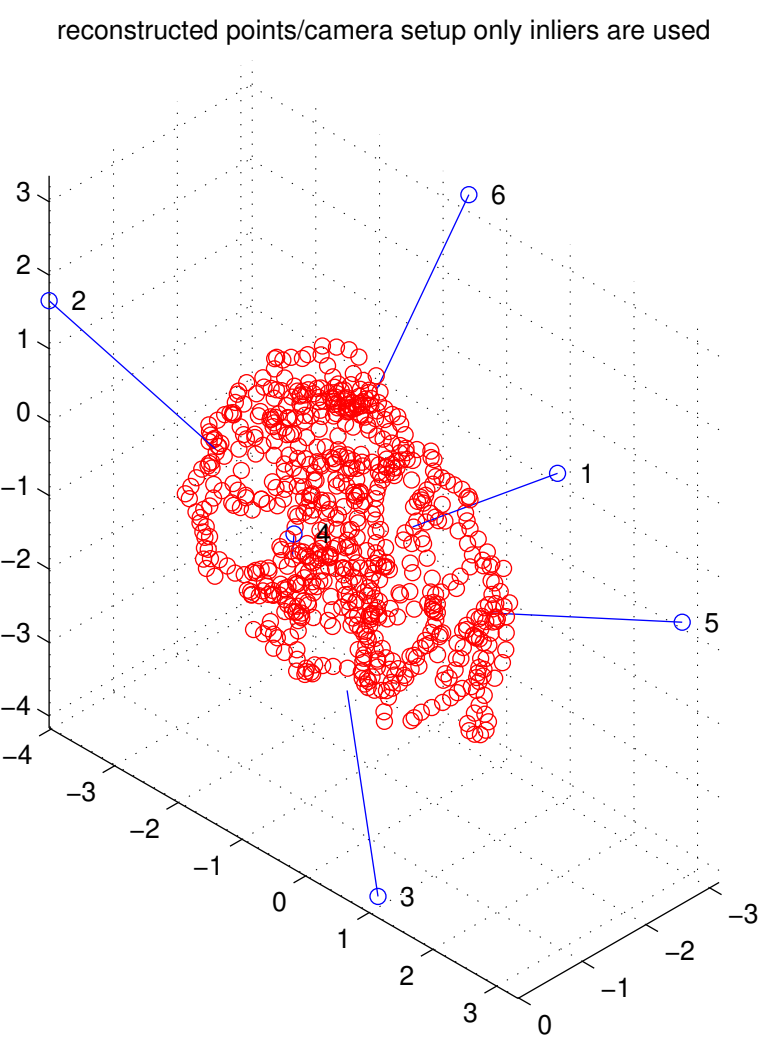
reconstructed points/camera setup only inliers are used
6
2
1
4
5
3
3
2
1
0
−1
−2
−3
−4
−4
−3
−2
−1
0
1
2
3
0
−1
−2
−3