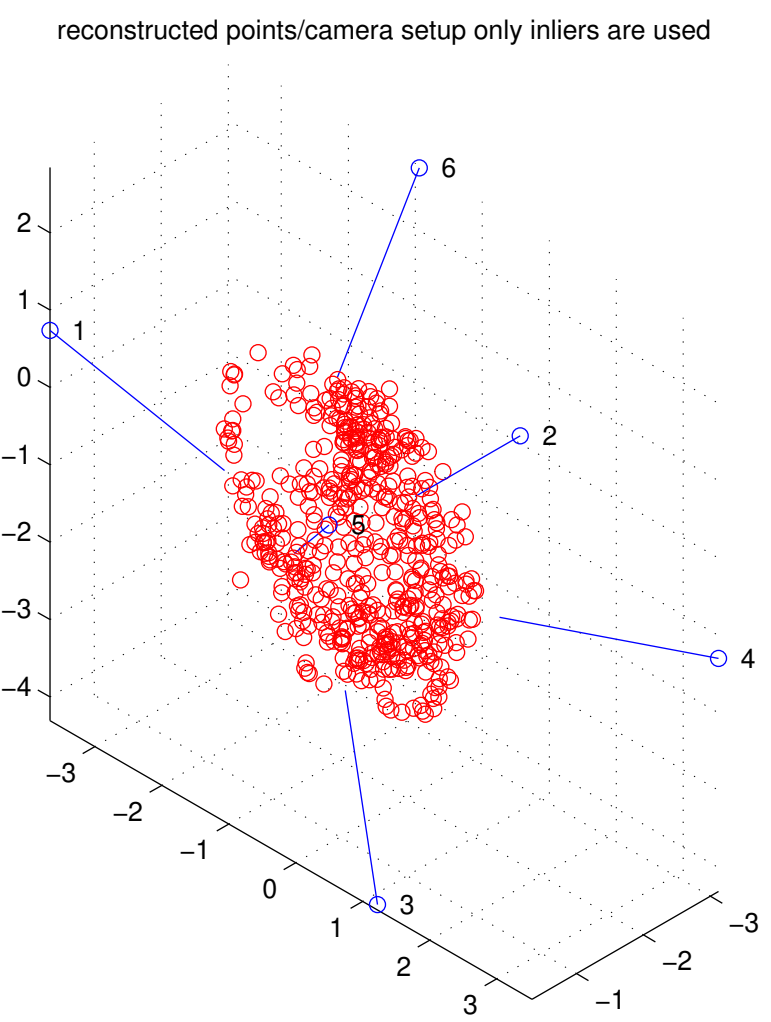
reconstructed points/camera setup only inliers are used
6
1
2
5
4
3
2
1
0
−1
−2
−3
−4
−3
−2
−1
0
1
2
3
−3
−2
−1