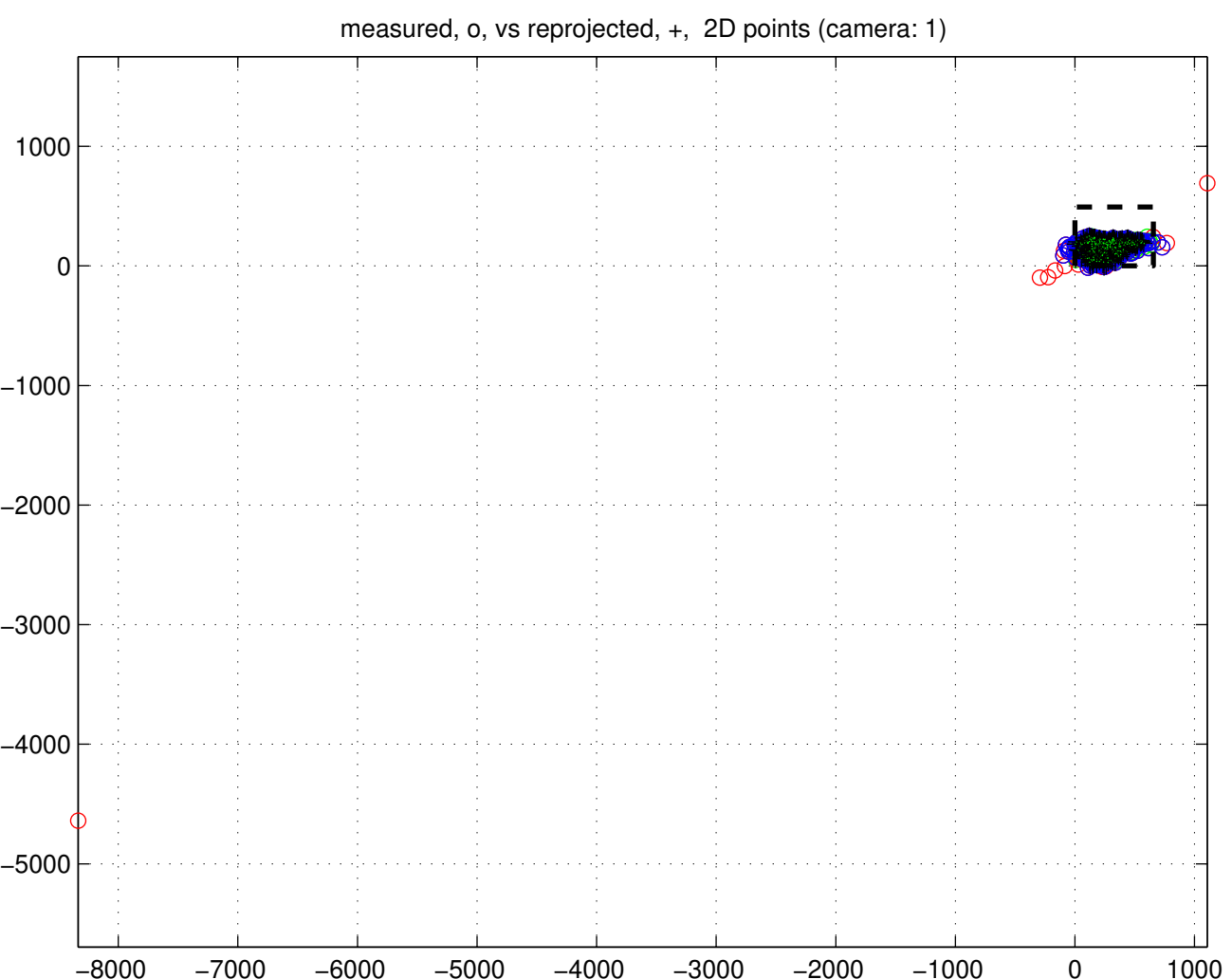
measured, o, vs reprojected, +, 2D points (camera: 1)
1000
0
−1000
−2000
−3000
−4000
−5000
−8000
−7000
−6000
−5000
−4000
−3000
−2000
−1000
0
1000