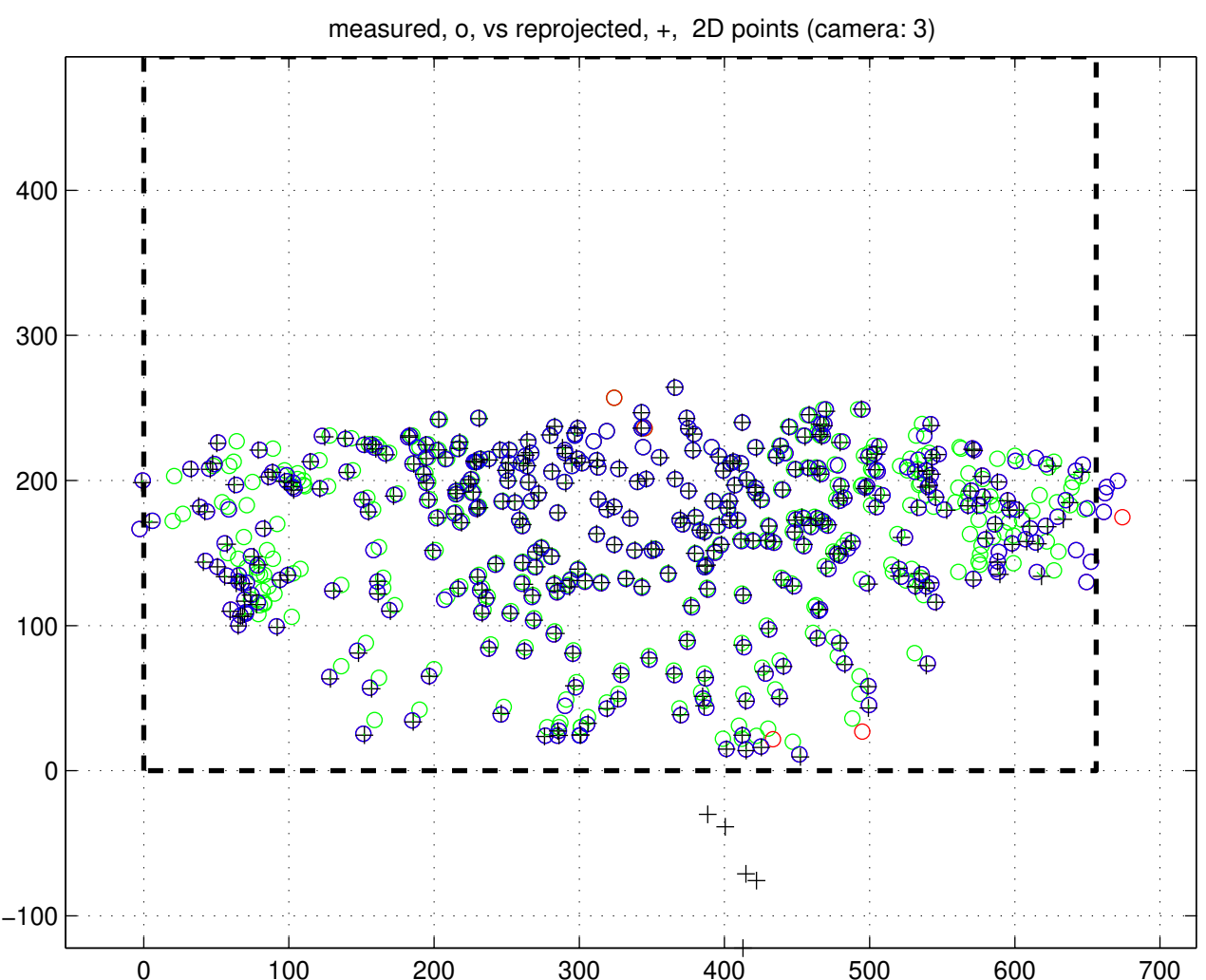
measured, o, vs reprojected, +, 2D points (camera: 3)
400
300
200
100
0
−100
0
100
200
300
400
500
600
700