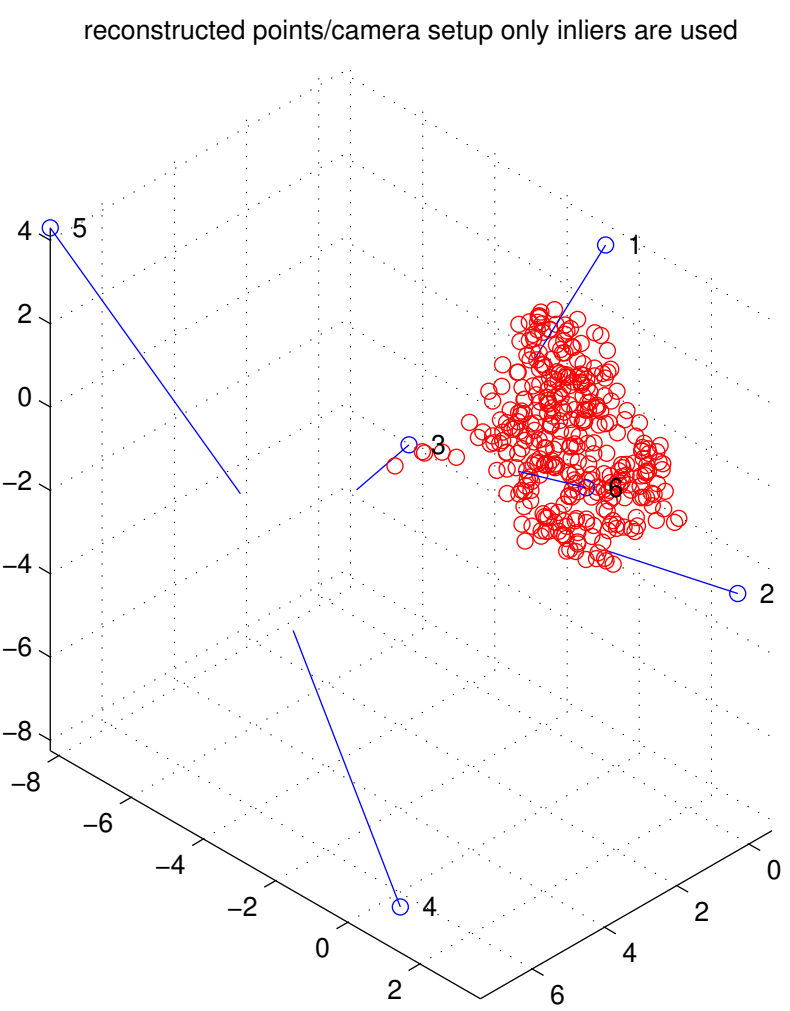
reconstructed points/camera setup only inliers are used
5
1
3
6
2
4
4
2
0
−2
−4
−6
−8
−8
−6
−4
−2
0
2
6
4
2
0