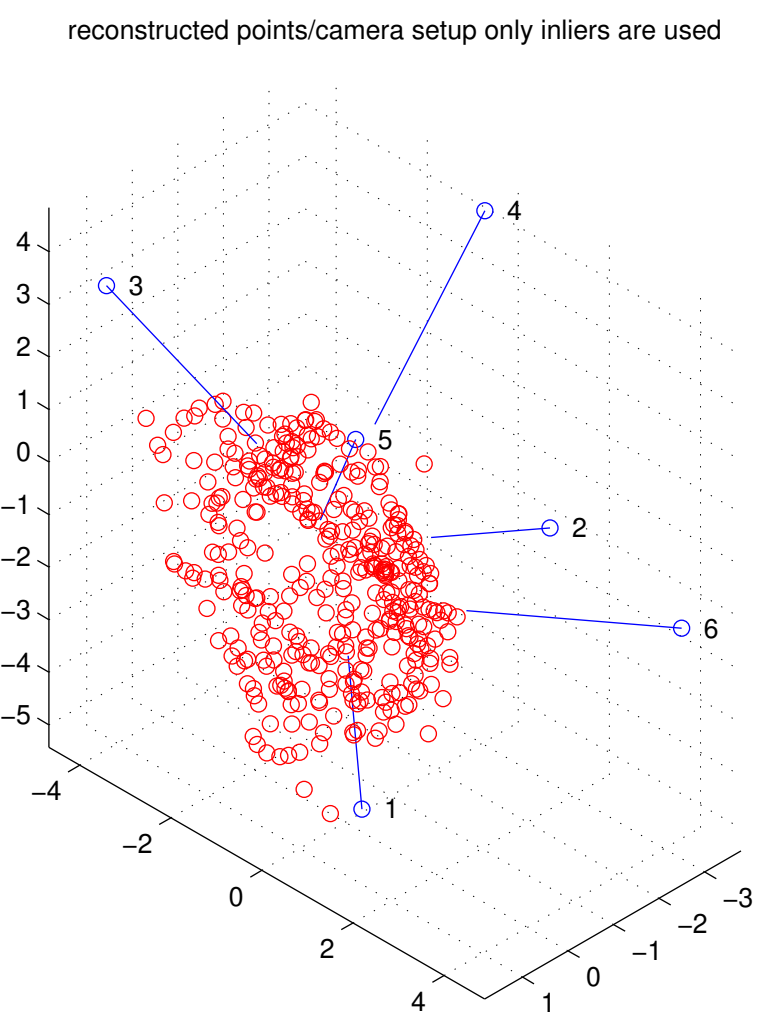
reconstructed points/camera setup only inliers are used
4
3
5
2
6
1
4
3
2
1
0
−1
−2
−3
−4
−5
−4
−2
0
2
4
−3
−2
−1
0
1