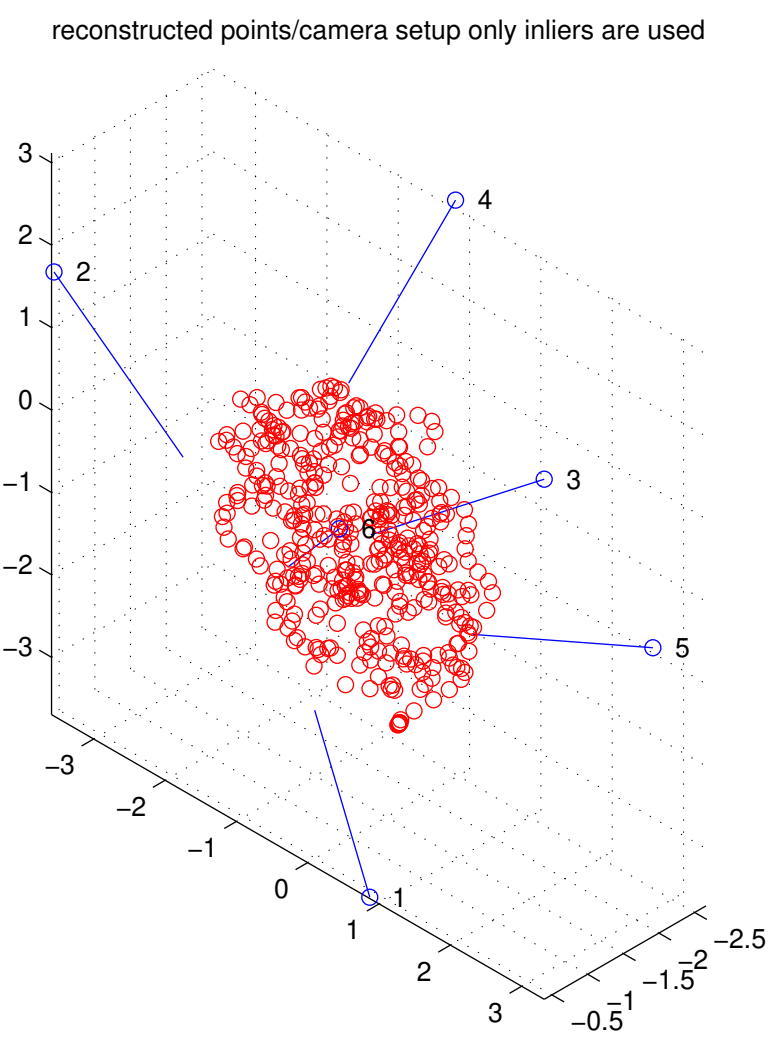
reconstructed points/camera setup only inliers are used
4
2
3
6
5
1
3
2
1
0
−1
−2
−3
−3
−2
−1
0
1
2
3
−2.5
−2
−1.5
−1
−0.5