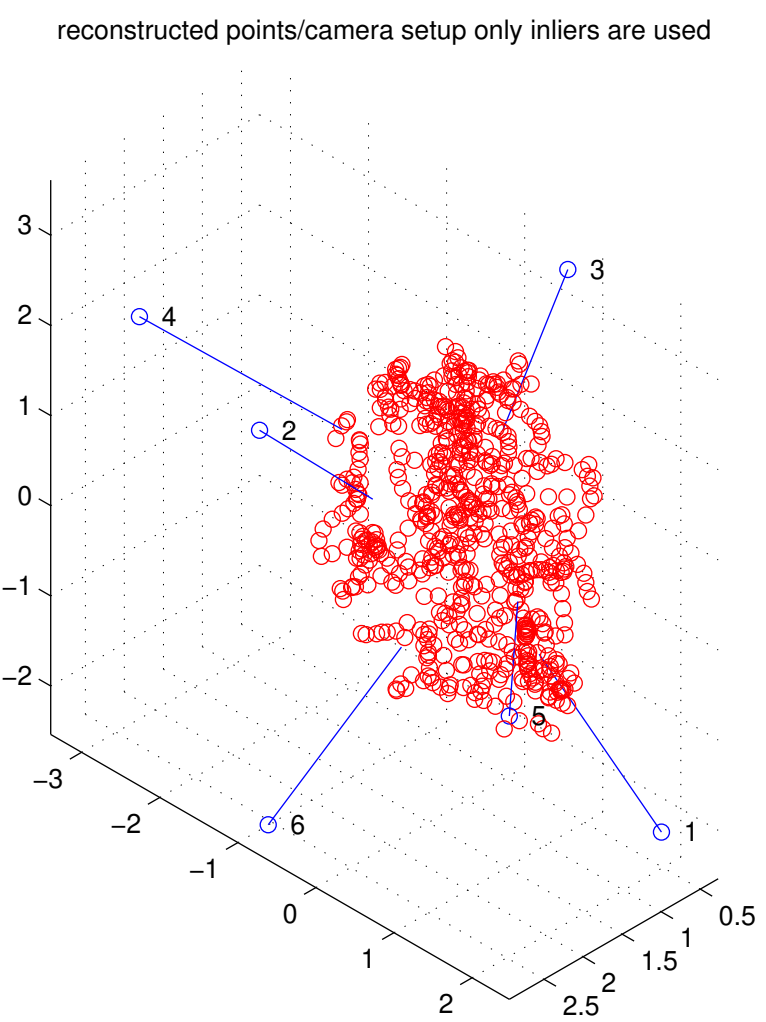
reconstructed points/camera setup only inliers are used
3
2
1
0
−1
−2
−3
−2
−1
0
1
2
0.5
1
1.5
2
2.5
1
2
3
4
5
6