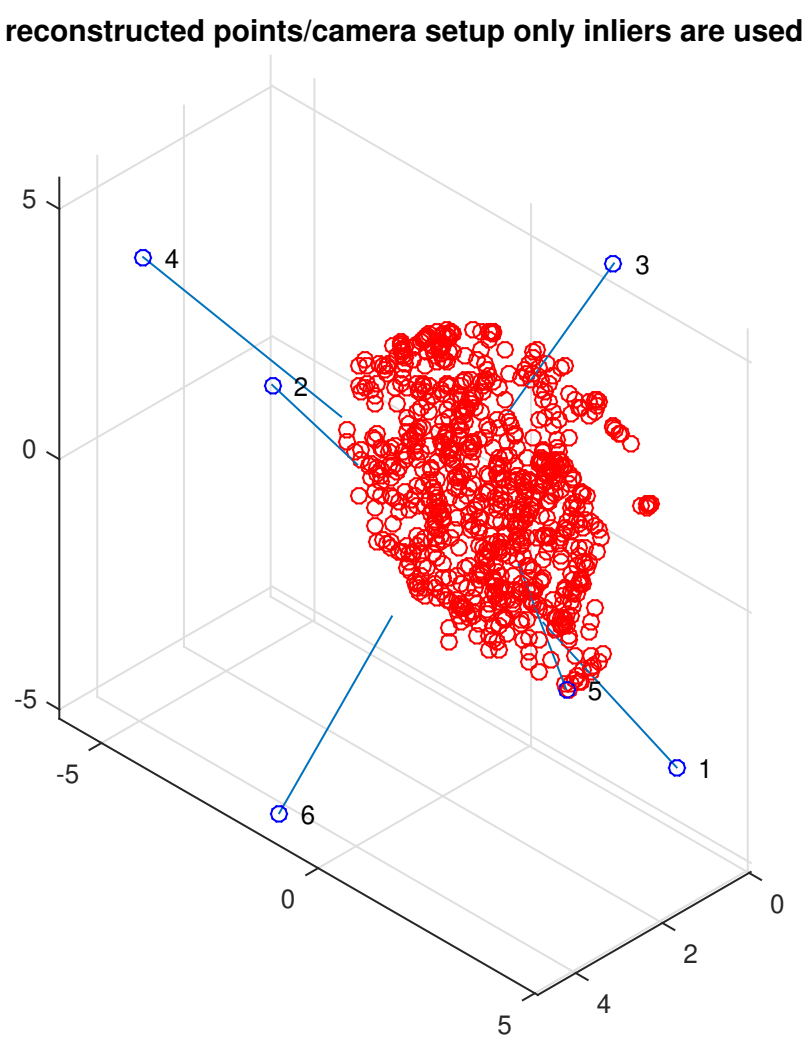
reconstructed points/camera setup only inliers are used
5
0
-5
-5
0
5
0
2
4
4
3
2
5
1
6