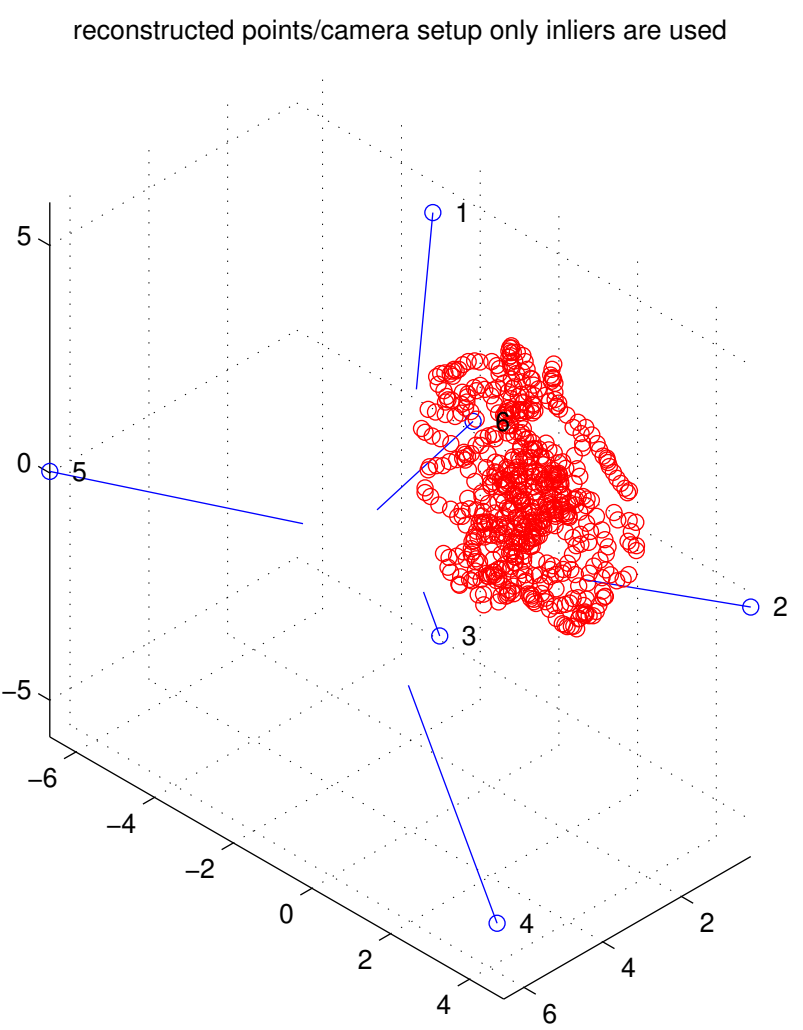
reconstructed points/camera setup only inliers are used
1
2
3
4
5
6
5
0
−5
−6
−4
−2
0
2
4
2
4
6