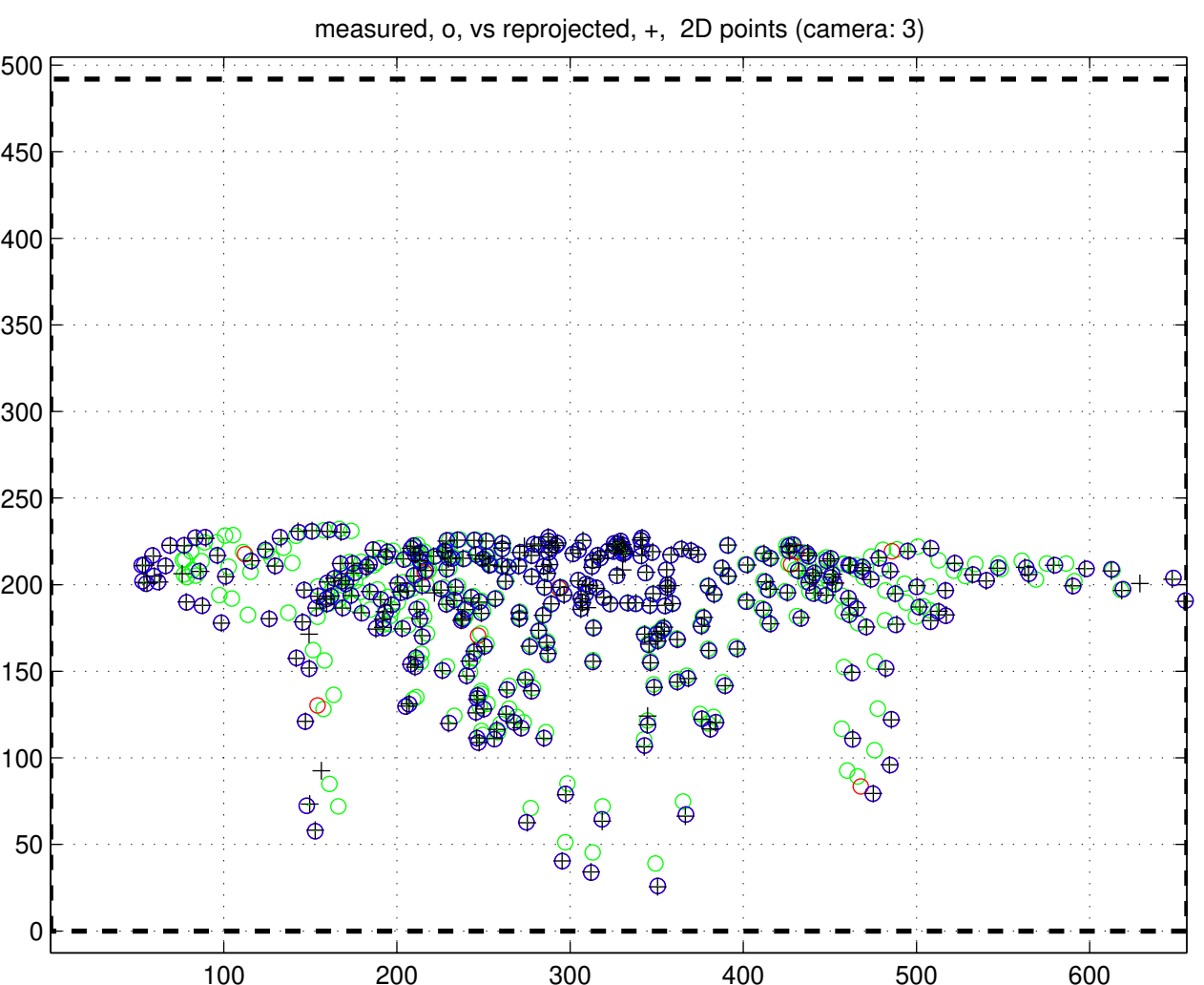
measured, o, vs reprojected, +, 2D points (camera: 3)
500
450
400
350
300
250
200
150
100
50
0
100
200
300
400
500
600