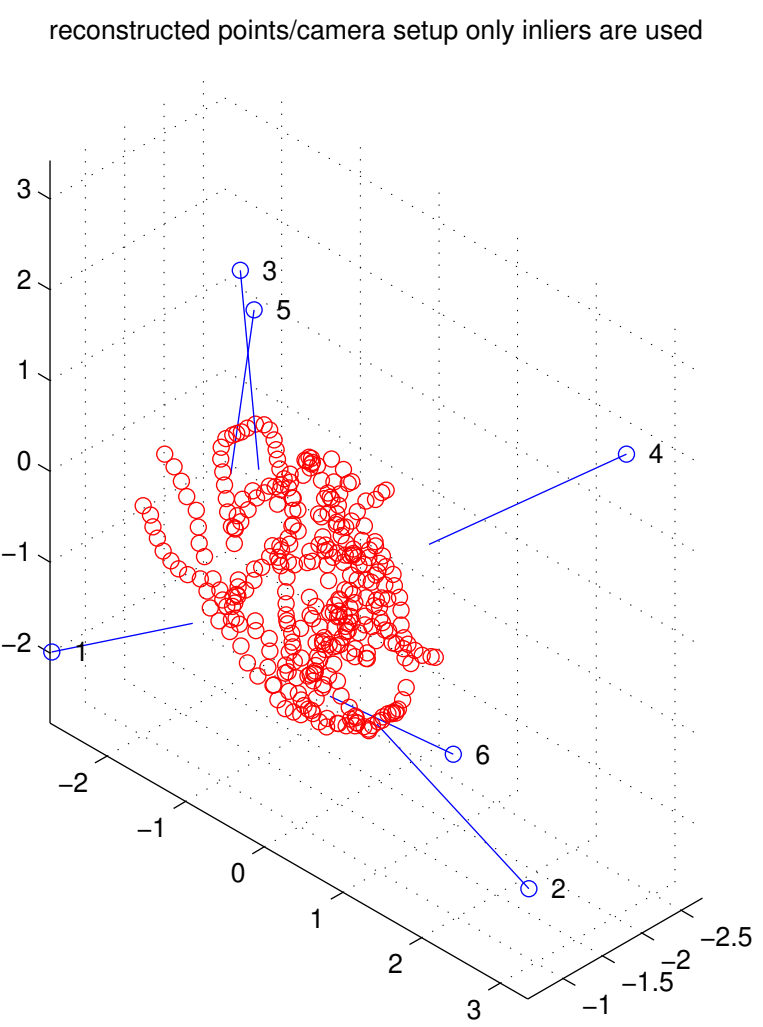
reconstructed points/camera setup only inliers are used
3
2
1
0
−1
−2
3
5
4
1
6
2
−2
−1
0
1
2
3
−2.5
−2
−1.5
−1