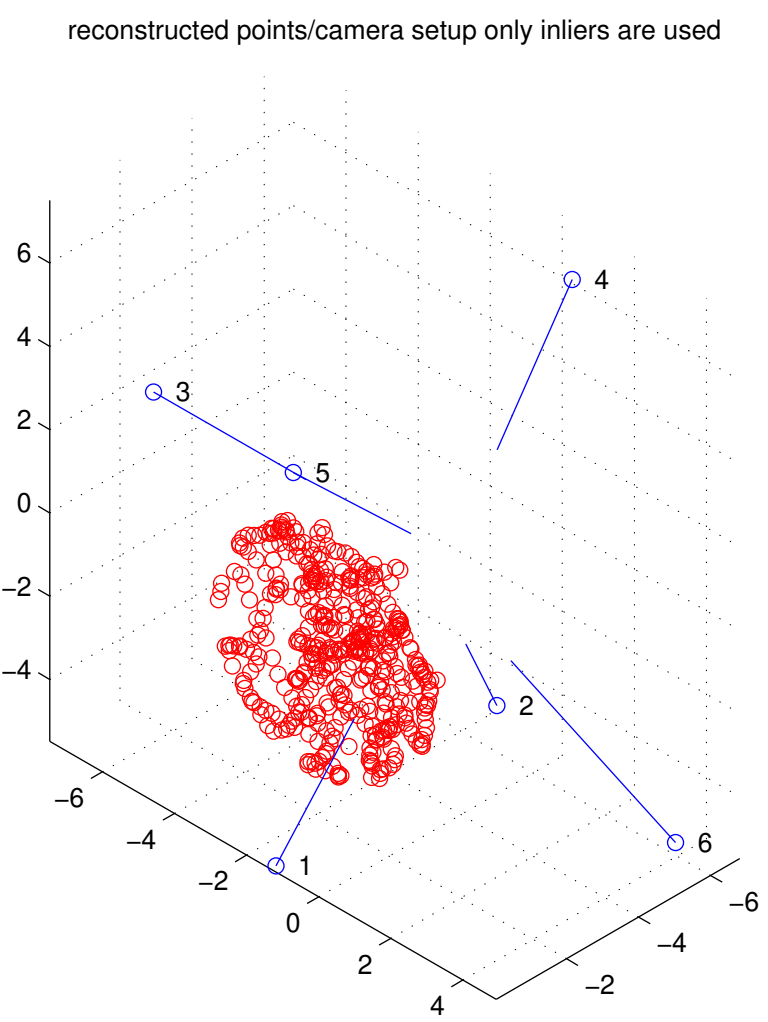
reconstructed points/camera setup only inliers are used
6
4
2
0
−2
−4
3
5
4
2
1
6
−6
−4
−2
0
2
4
−6
−4
−2