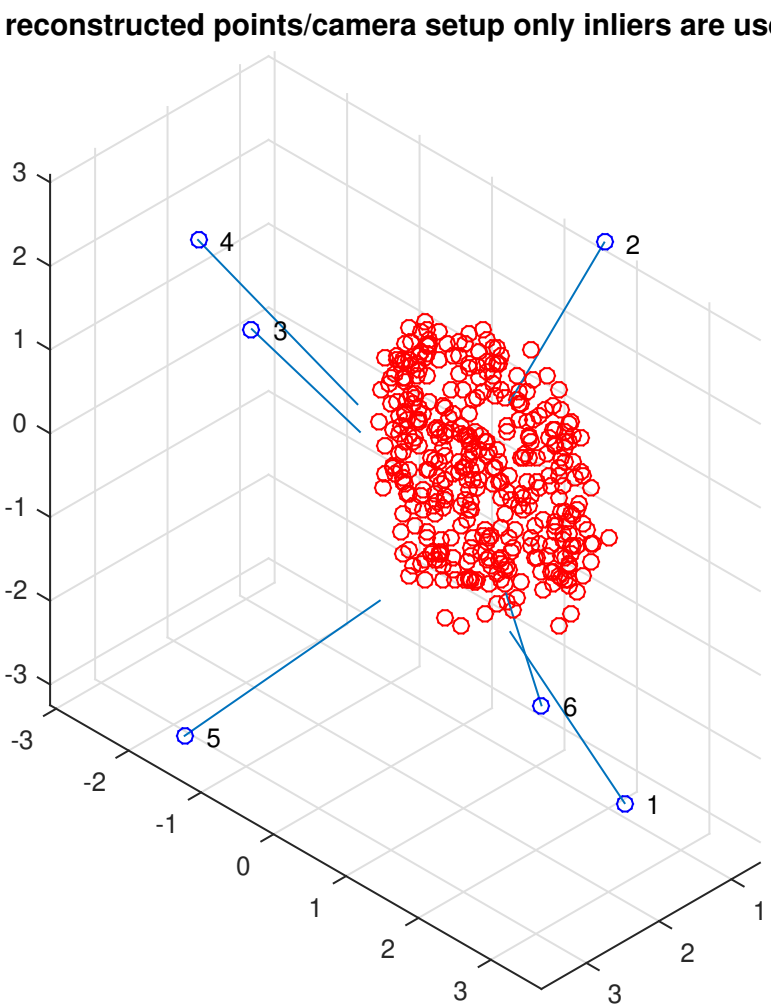
reconstructed points/camera setup only inliers are used
4
2
3
5
6
1
3
2
1
0
-1
-2
-3
-3
-2
-1
0
1
2
3
1
2
3