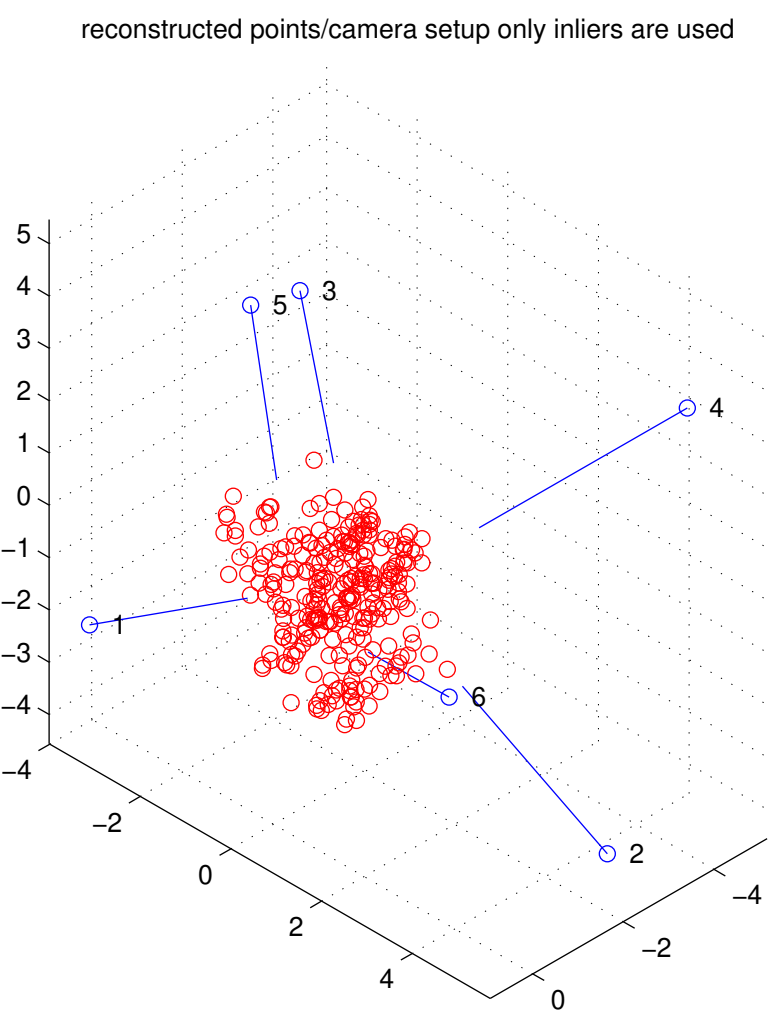
reconstructed points/camera setup only inliers are used
5
4
3
2
1
0
−1
−2
−3
−4
5
3
4
1
6
2
−4
−2
0
2
4
−4
−2
0