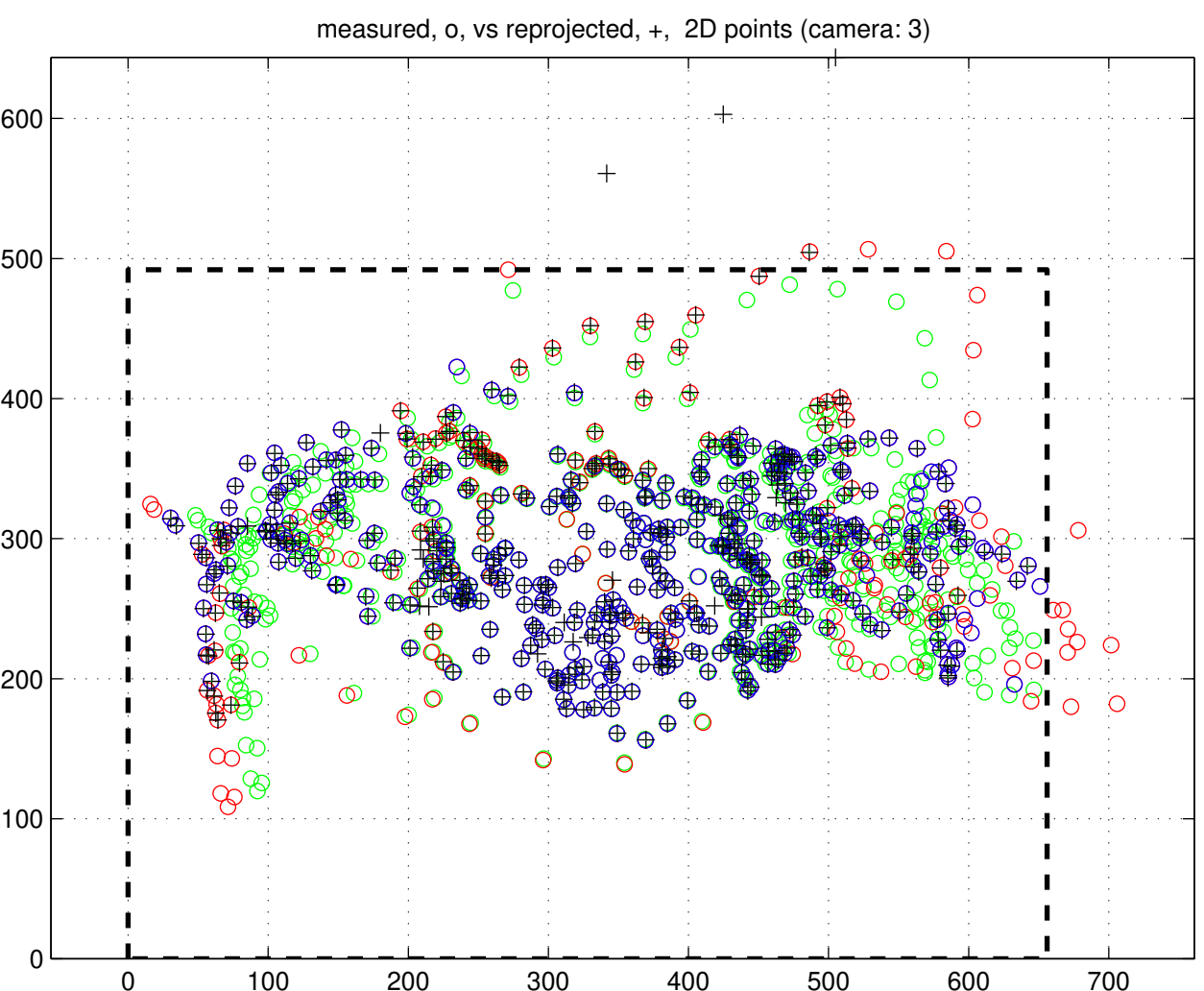
measured, o, vs reprojected, +, 2D points (camera: 3)
0
100
200
300
400
500
600
700