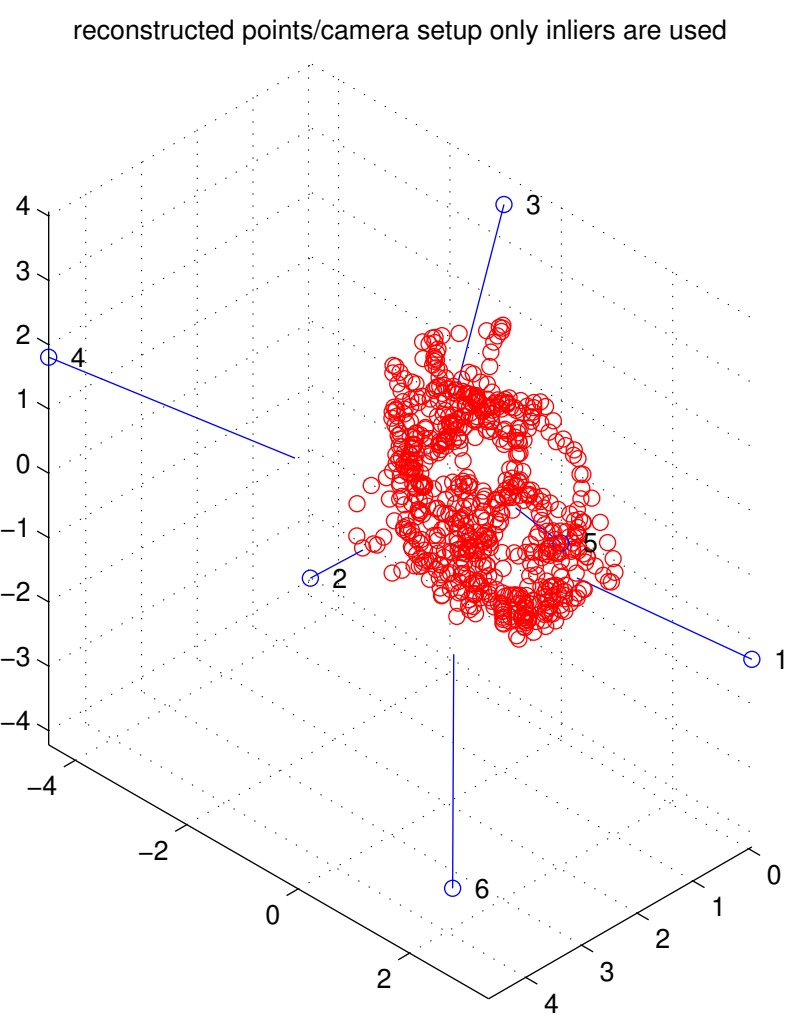
reconstructed points/camera setup only inliers are used
4
3
2
1
0
−1
−2
−3
−4
3
4
2
5
1
6
−4
−2
0
2
4
0
1
2
3