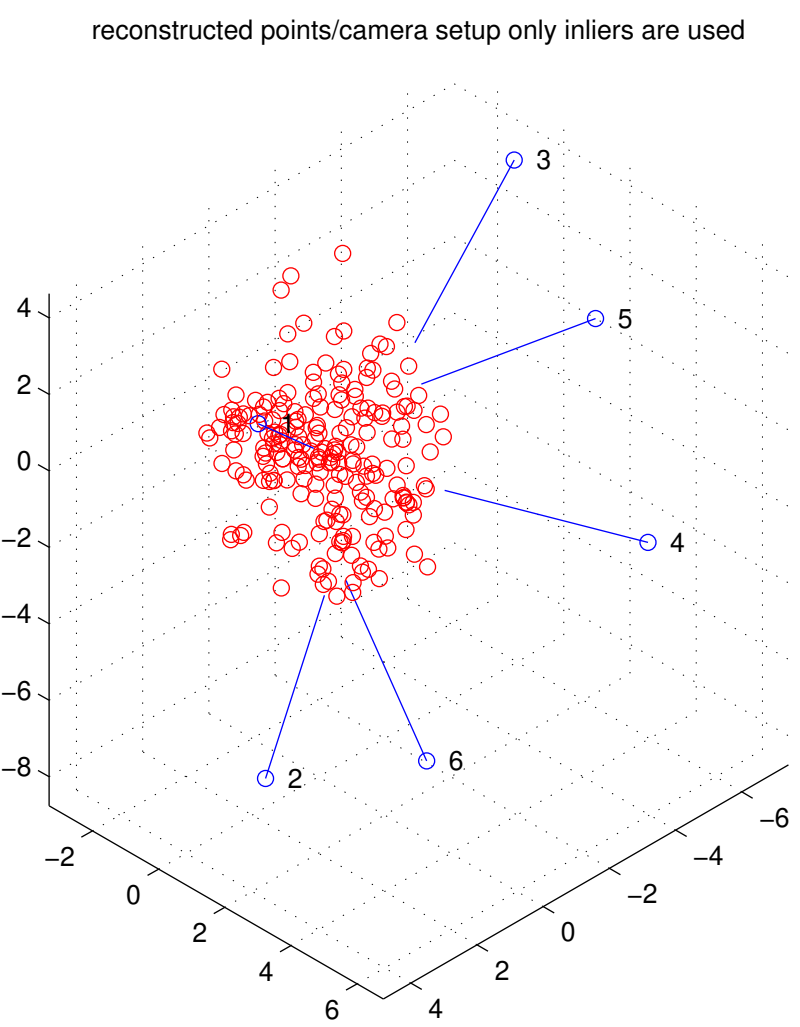
reconstructed points/camera setup only inliers are used
1
2
3
4
5
6
4
2
0
−2
−4
−6
−8
−2
0
2
4
6
4
2
0
−2
−4
−6