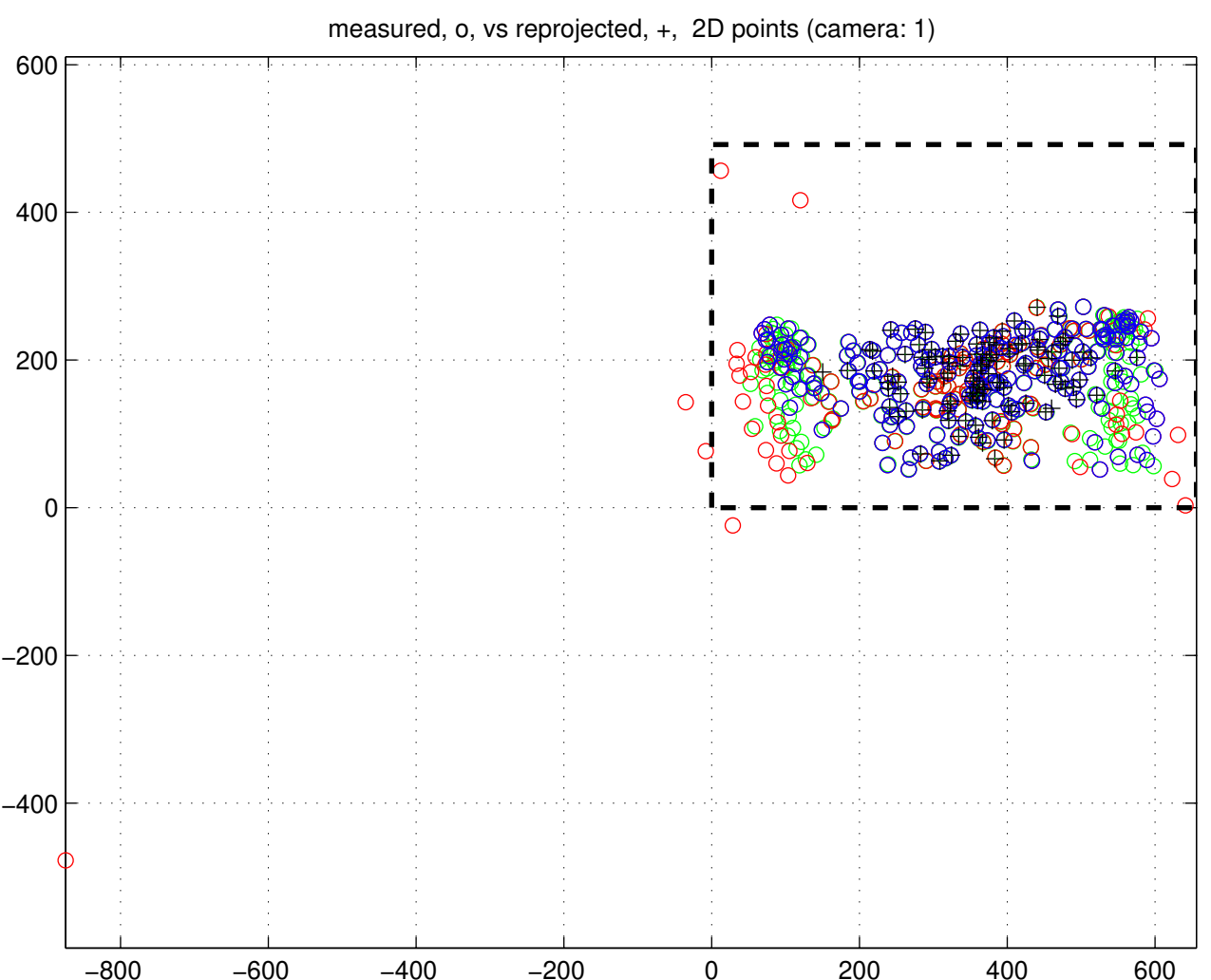
measured, o, vs reprojected, +, 2D points (camera: 1)
600
400
200
0
−200
−400
−800
−600
−400
−200
0
200
400
600