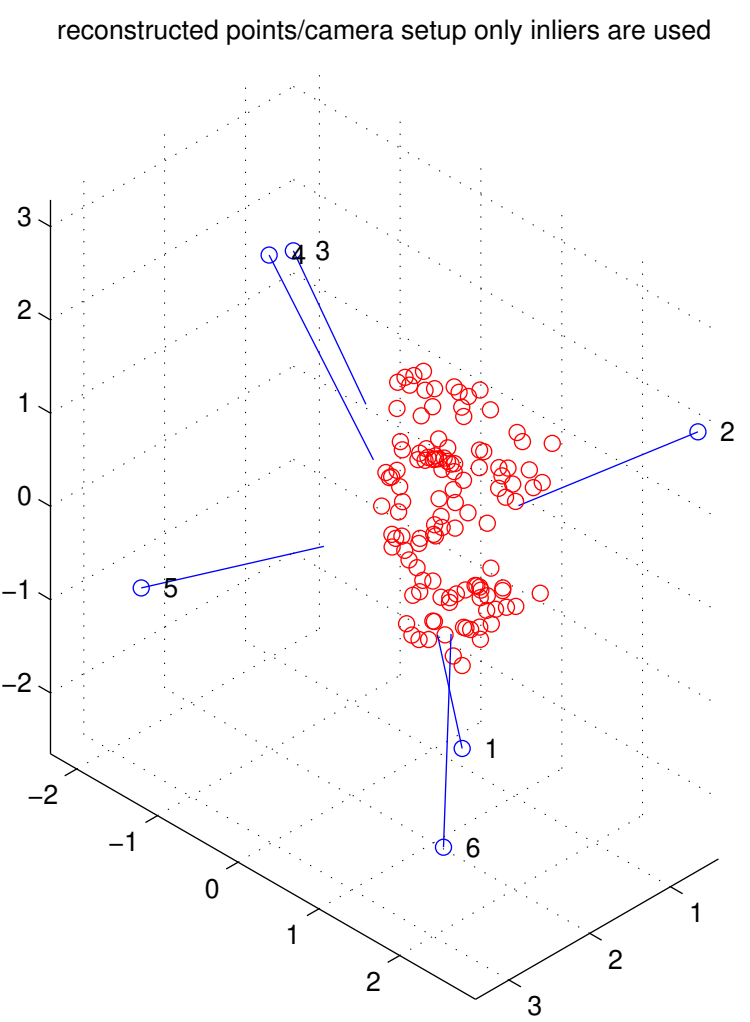
reconstructed points/camera setup only inliers are used
3
2
1
0
−1
−2
4
3
2
5
1
6
−2
−1
0
1
2
3
1
2