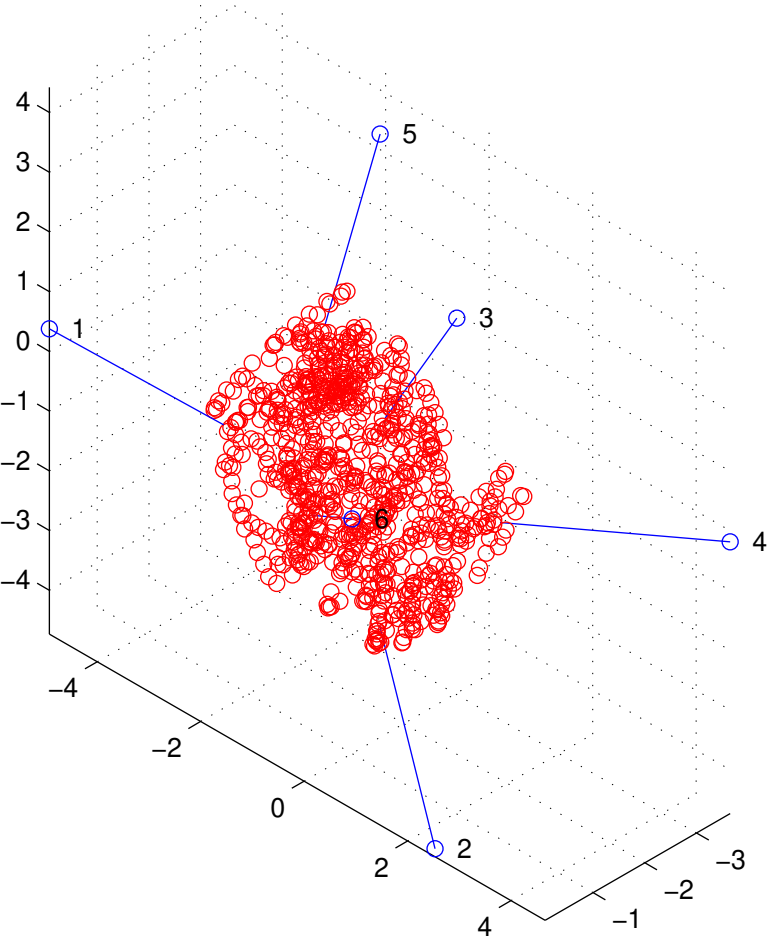reconstructed points/camera setup only inliers are used