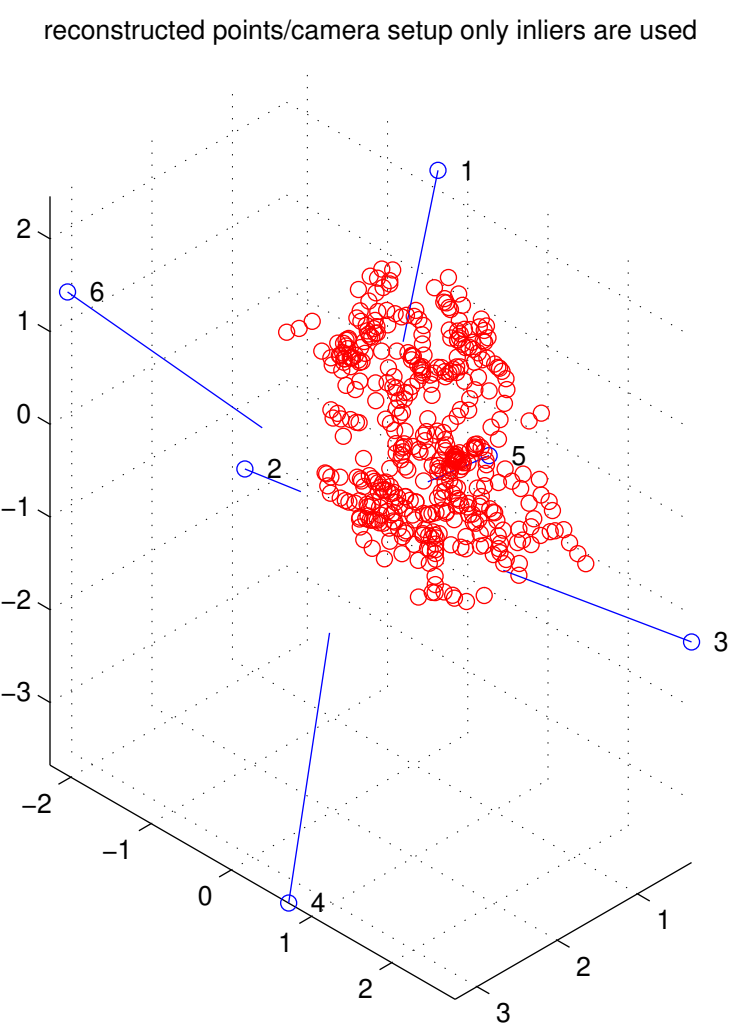
reconstructed points/camera setup only inliers are used
1
2
3
4
5
6
2
1
0
−1
−2
−3
−2
−1
0
1
2
3
1
2
3