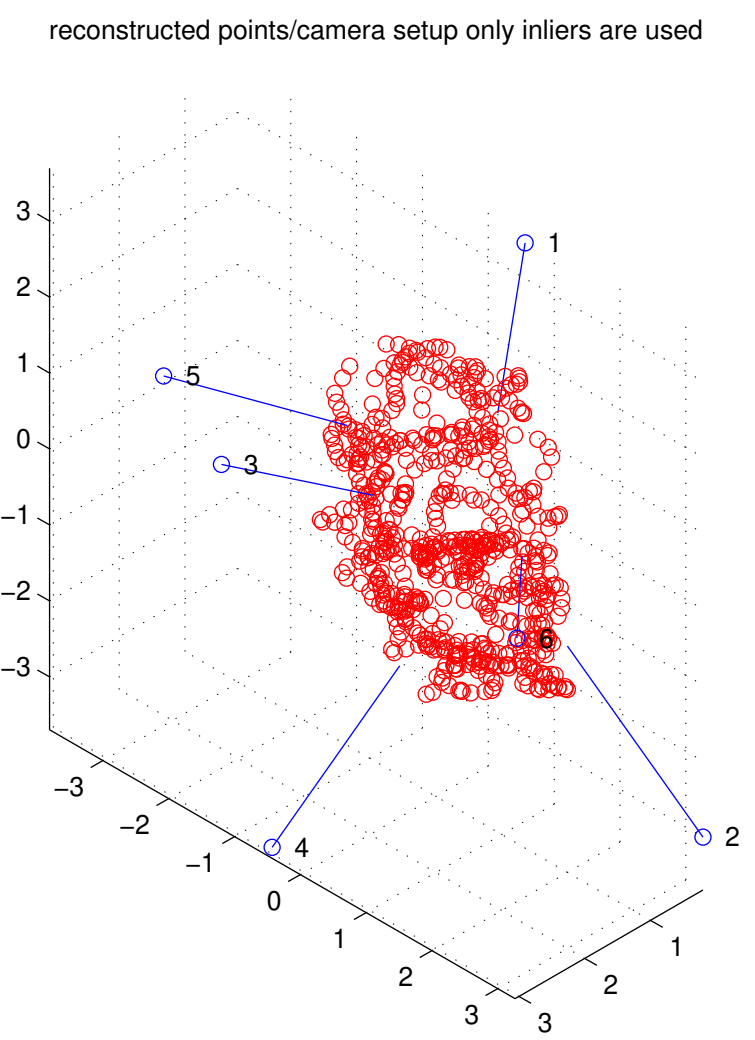
reconstructed points/camera setup only inliers are used
1
2
3
4
5
6
3
2
1
0
−1
−2
−3
−3
−2
−1
0
1
2
3
3
2
1