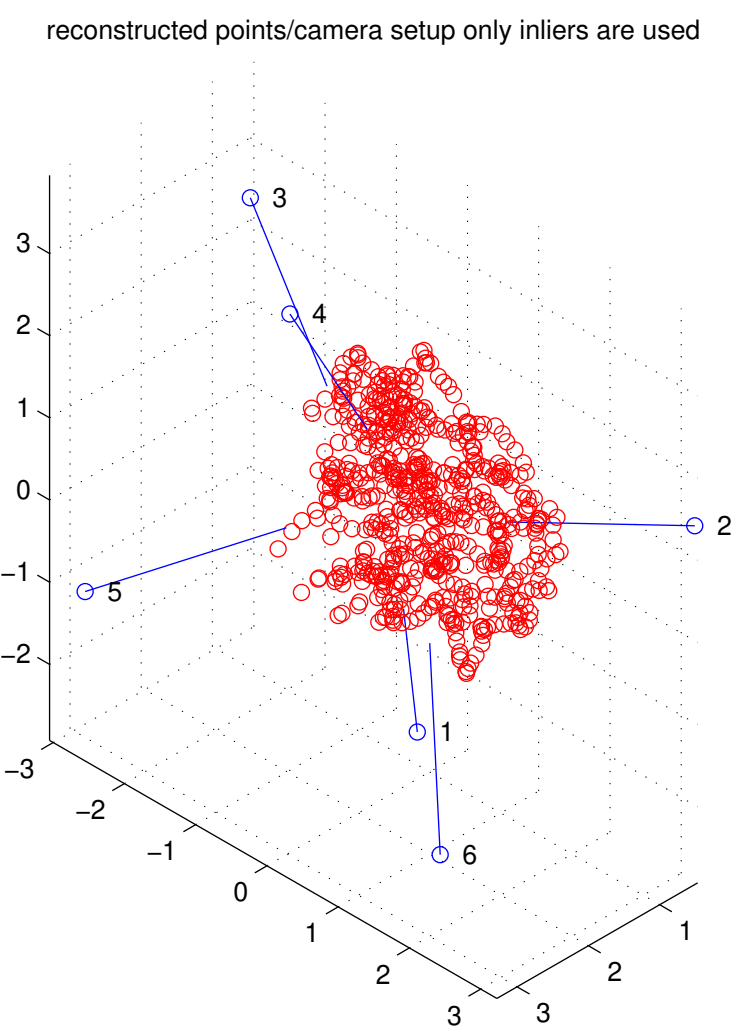
reconstructed points/camera setup only inliers are used
3
4
2
5
1
6
3
2
1
0
−1
−2
−3
−2
−1
0
1
2
3
3
2
1