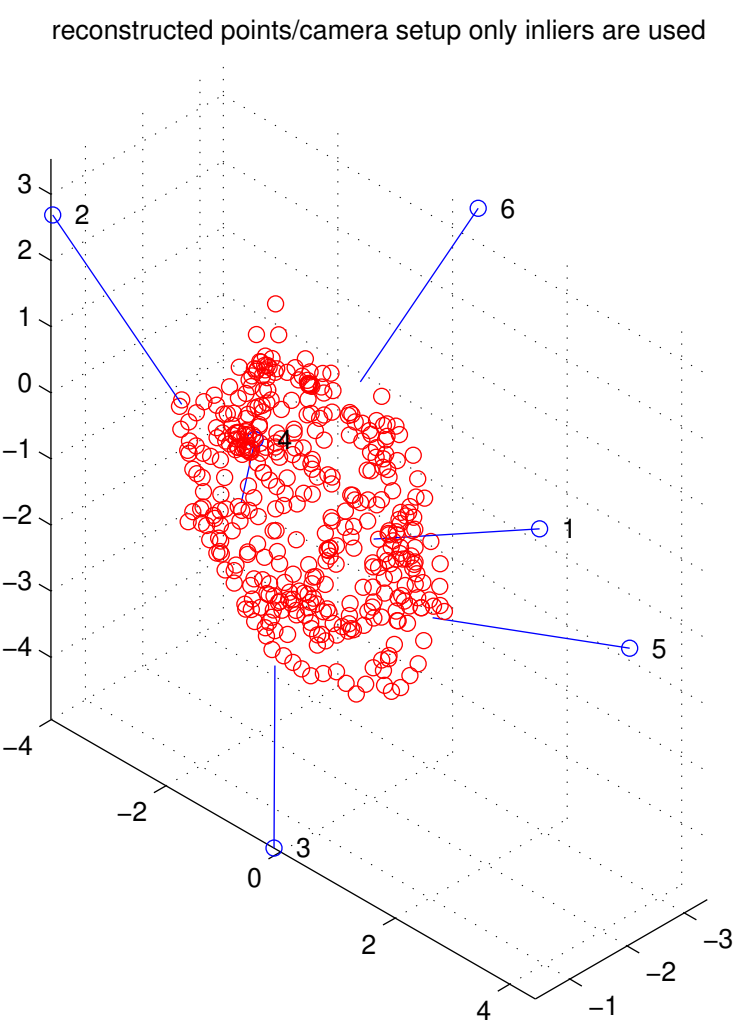
reconstructed points/camera setup only inliers are used
2
6
4
1
5
3
3
2
1
0
−1
−2
−3
−4
−4
−2
0
2
4
−3
−2
−1