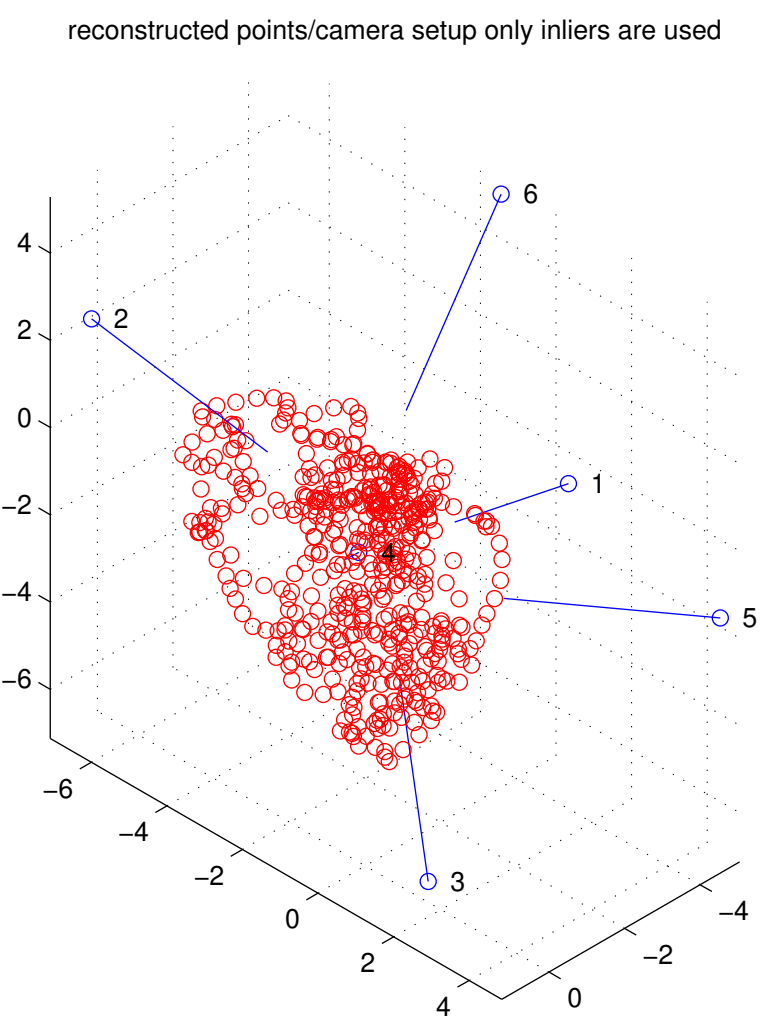
reconstructed points/camera setup only inliers are used
6
2
1
4
5
3
4
2
0
−2
−4
−6
−6
−4
−2
0
2
4
−4
−2
0