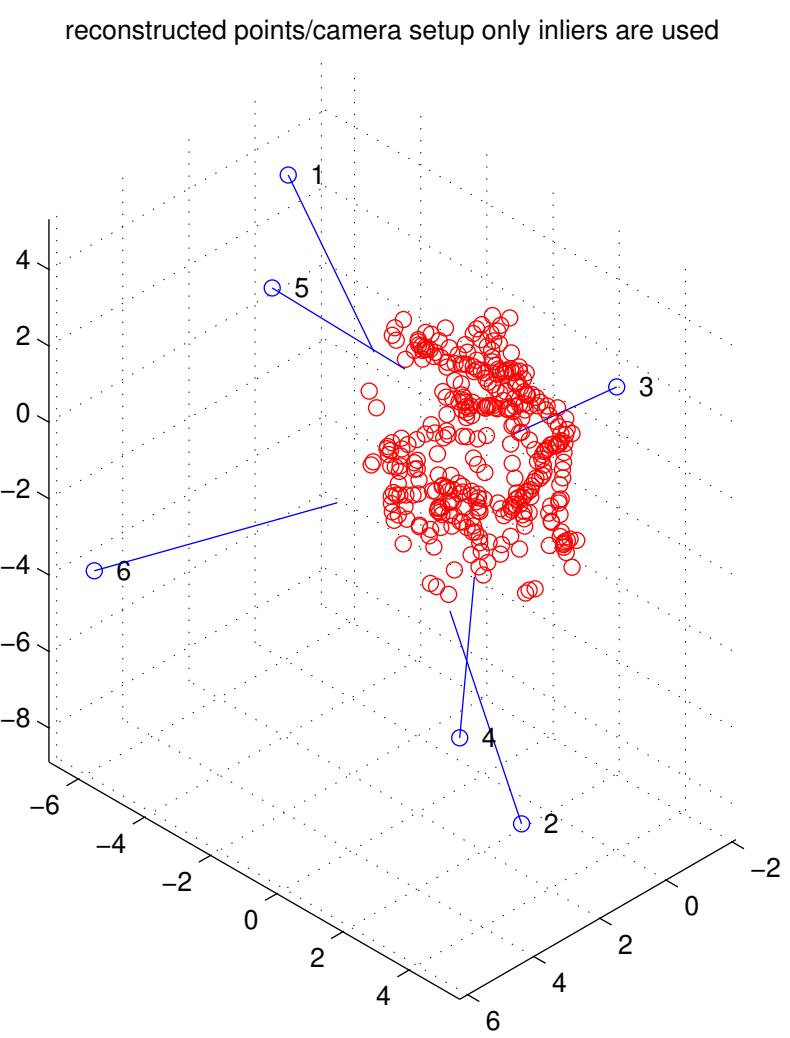
reconstructed points/camera setup only inliers are used
1
5
3
6
4
2
4
2
0
−2
−4
−6
−8
−6
−4
−2
0
2
4
6
−2
0
2
4